# Existence for a class of fourth-order quasilinear parabolic equations



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joint work with Y. Giga

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#### Motivation

Macroscopic models of thermodynamic fluctuations of crystal surfaces

$$u_t = \operatorname{div} \left( \mathbb{M}(\nabla u) \nabla f(-\operatorname{div} D\Phi(\nabla u)) \right) \\ = -\operatorname{div} \left( \mathbb{M}(\nabla u) f'(-\operatorname{div} D\Phi(\nabla u)) \nabla \operatorname{div} D\Phi(\nabla u) \right)$$

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physical choices:

If 
$$(p) = e^p$$
,  $f(p) = p$ 
If  $(\xi) \sim |\xi|^p$ ,  $p > 1$  (Marzuola-Weare 2013)
If  $(\xi) \sim |\xi|$  (Liu-Lu-Margetis-Marzuola 2017)
If  $(\xi) \sim |\xi| + |\xi|^3$  (Margetis-Kohn 2006)
If  $(\xi) \sim \begin{bmatrix} 1 & 0 \\ 0 & (1+|\xi|)^{-1} \end{bmatrix}$ ,  $\mathbb{M}(\xi) \sim \mathbb{U}(\xi)^T \begin{bmatrix} 1 & 0 \\ 0 & (1+|\xi|)^{-1} \end{bmatrix} \mathbb{U}(\xi)$  (Margetis-Kohn 2006)

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with  $M(\boldsymbol{\xi}) \sim \mathbb{U}(\boldsymbol{\xi})^T \begin{bmatrix} 1 & 0\\ 0 & (1 + |\boldsymbol{\xi}|)^{-1} \end{bmatrix} \mathbb{U}(\boldsymbol{\xi})$  (Xu, 2020)

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- numerics for discretization of u<sub>t</sub> = -dive<sup>-ψ<sub>ε</sub>\*Δ<sub>1</sub>u</sup>∇Δ<sub>1</sub>u, stability of spatial discretization (Craig-Liu-Lu-Marzuola-Wang, 2022)
- existence for  $u_t = \Delta \exp(-\Delta_p u)$ , 1 (Price-Xu, 2023)

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- existence results rely on gradient flow formulations or monotonicity

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• 
$$\mathcal{F}(u) = \int_{\Omega} \exp(-\Delta u)$$
,  $u_t = \Delta \exp(-\Delta u)$  (Gao-Liu-Lu 2019)

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#### Monotone operators

$$u_t = \mathcal{L}(u)$$
$$\langle \mathcal{L}(v) - \mathcal{L}(w), v - w \rangle \le 0$$

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General existence result using Galerkin method by Vishik (1962) for parabolic systems of form

$$\boldsymbol{u}_t + (-1)^n \operatorname{div}^n \mathbb{L}(t, x, \boldsymbol{u}, \nabla \boldsymbol{u}, \dots, \nabla^n \boldsymbol{u}) = \boldsymbol{g}(t, x)$$

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Example:

•  $\Phi(\boldsymbol{\xi}) = |\boldsymbol{\xi}|, u_t = -\Delta \operatorname{div} \frac{\nabla u}{|\nabla u|}$  (Giga-Giga 2010, Giga-Kuroda-Matsuoka 2014, Giga-Kuroda-Ł 2023)

$$\mathbb{B} = \mathbb{B}(t, x), \quad (v, w)_{\dot{H}_{\mathbb{B}(t, \cdot)}^{-1}(\Omega)} = \int_{\Omega} v(-\operatorname{div} \mathbb{B}(t, \cdot) \, \nabla)^{-1} w$$

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Damlamian, 1974: existence of  $H_{\mathbb{R}}^{-1}$  gradient flows assuming

■  $t \mapsto \mathbb{B}(t, \cdot)$  is a family of uniformly equivalent scalar products on  $\mathbb{R}^n$ ■  $\mathbb{B} \in W^{1,1}(0, T, L^{\infty}(\Omega))$   $W_q$  — a metric on the space of probability measures with finite q-th moment

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Examples:

•  $\mathcal{F}(u) = \int_{\Omega} |\nabla u|^2$ ,  $u_t = -\text{div}u\nabla\Delta u$ , lubrication problems (Otto, 1998; Giacomelli-Otto 2001)

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•  $u_t = -\operatorname{div} b(u) \nabla(\Delta u - g(u))$  (Lisini-Matthes-Savaré 2012)

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- $u_t = -\operatorname{div} b(u) \nabla(\Delta u g(u))$  (Lisini-Matthes-Savaré 2012)
- div B(u) ∇ via Wasserstein metrics (Mielke, 2011; Liero-Mielke 2013)

#### Basic result: assumptions

$$\boldsymbol{u}_t + \operatorname{div} \mathcal{B}(\boldsymbol{u}) \nabla \mathcal{A}(\boldsymbol{u}) = \operatorname{div} \boldsymbol{g}$$
 (\*)

- for simplicity  $\Omega = \mathbb{T}^n$
- $\mathcal{A}(\boldsymbol{u}) = \operatorname{div} D_{\boldsymbol{\xi}} \Phi(\boldsymbol{x}, \nabla \boldsymbol{u})$
- $\Phi$  is convex and  $C^1$  with respect to the gradient variable,

$$c_0(|\boldsymbol{\xi}|^p - 1) \le \Phi(x, \boldsymbol{\xi}), \qquad |D_{\boldsymbol{\xi}}\Phi(x, \boldsymbol{\xi})| \le c_1(|\boldsymbol{\xi}|^{p-1} + 1)$$

with  $p > \max(1, \frac{2n}{n+4})$ 

B(u) = B(t, x, u, ∇u, A(u)) with a Carathéodory function B taking values in L(ℝ<sup>nN</sup>, ℝ<sup>nN</sup>) satisfying

$$\mu \mathbb{I} \leq \mathbb{B} \leq M \mathbb{I}$$

• 
$$\boldsymbol{g} = \boldsymbol{g}(t, x) \in L^2(]0, T[\times \Omega)^{nN}$$
$$\boldsymbol{u}_t + \operatorname{div} \mathcal{B}(\boldsymbol{u}) \nabla \mathcal{A}(\boldsymbol{u}) = \operatorname{div} \boldsymbol{g}$$
 (\*)

#### Theorem (Giga-Ł, in preparation)

Let  $u_0 \in W^{1,p}(\Omega)$  and let T > 0. There exists a weak solution to (\*) in  $]0, T[\times \Omega$  with initial datum  $u_0$  satisfying energy inequality

$$\begin{split} \sup_{0 < t < T} \int_{\Omega} \Phi(\cdot, \nabla \boldsymbol{u}) + \frac{1}{2} \int_{0}^{T} \!\!\!\!\int_{\Omega} \nabla \mathcal{A}(\boldsymbol{u}) \colon \mathcal{B}(\boldsymbol{u}) \nabla \mathcal{A}(\boldsymbol{u}) \\ & \leq 2 \int_{\Omega} \Phi(\cdot, \nabla \boldsymbol{u}_{0}) + \frac{1}{\mu} \int_{0}^{T} \!\!\!\!\int_{\Omega} |\boldsymbol{g}|^{2}. \end{split}$$

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$$\boldsymbol{u}_{j,t} + \operatorname{div} \mathcal{P}_j \left( \mathcal{B}_j(\boldsymbol{u}_j) \nabla \mathcal{A}_j(\boldsymbol{u}_j) \right) = \operatorname{div} \mathcal{P}_j \boldsymbol{g},$$

where  $\mathcal{P}_{j}$  – projection onto first j eigenvectors and

 $\mathcal{A}_j(\boldsymbol{w}) = \operatorname{div} \mathcal{P}_j D_{\boldsymbol{\xi}} \Phi(x, \nabla \boldsymbol{w}), \quad \mathcal{B}_j(\boldsymbol{w}) = \mathbb{B}(t, x, \boldsymbol{w}, \nabla \boldsymbol{w}, \mathcal{A}_j(\boldsymbol{w}))$ 

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by boundedness of energy and monotonicity we have strong convergence ∇u<sub>j</sub> → ∇u, D<sub>ξ</sub>Φ(·, ∇u<sub>j</sub>) → D<sub>ξ</sub>Φ(·, ∇u)

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satisfy energy inequality

- by boundedness of energy and monotonicity we have strong convergence  $\nabla u_j \rightarrow \nabla u$ ,  $D_{\boldsymbol{\xi}} \Phi(\cdot, \nabla u_j) \rightarrow D_{\boldsymbol{\xi}} \Phi(\cdot, \nabla u)$
- using the  $L^2$  bound on  $\nabla A_j(w)$  and interpolation, we obtain strong convergence of  $A_j(u_j)$  and then  $\mathcal{B}_j(u_j)$

#### Galerkin approximation

 $\omega_1, \omega_2, \ldots$  — orthogonal eigenbasis of  $\Delta$  on  $L^2_{av}(\Omega)^N$  $\nabla \omega_1, \nabla \omega_2, \ldots$  — orthogonal eigenbasis of  $\nabla \operatorname{div} = \Delta$  on  $L^2_{\nabla}(\Omega)^{nN}$ 

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$$\mathcal{A}_j(\boldsymbol{w}) = \operatorname{div} \mathcal{P}_j D_{\boldsymbol{\xi}} \Phi(x, \nabla \boldsymbol{w}), \quad \mathcal{B}_j(\boldsymbol{w}) = \mathbb{B}(t, x, \boldsymbol{w}, \nabla \boldsymbol{w}, \mathcal{A}_j(\boldsymbol{w})).$$

$$\boldsymbol{u}_{j,t} + \operatorname{div} \mathcal{P}_j \left( \mathcal{B}_j(\boldsymbol{u}_j) \nabla \mathcal{A}_j(\boldsymbol{u}_j) \right) = \operatorname{div} \mathcal{P}_j \boldsymbol{g},$$

 $\boldsymbol{u}_j(0,\cdot) = \boldsymbol{u}_{0,j}$  — projection onto  $\operatorname{span}(\boldsymbol{e}_1,\ldots,\boldsymbol{e}_N,\boldsymbol{\omega}_1,\ldots,\boldsymbol{\omega}_j).$ 

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$$\boldsymbol{u}_j(t,\cdot) = (a_1,\ldots,a_N) + \sum_{i=1}^j a_{ji}(t)\boldsymbol{\omega}_i,$$

$$\frac{\mathrm{d}}{\mathrm{d}t} \int_{\Omega} \Phi(\cdot, \nabla \boldsymbol{u}_j) = \int_{\Omega} D_{\boldsymbol{\xi}} \Phi(\cdot, \nabla \boldsymbol{u}_j) : \nabla \boldsymbol{u}_{j,t}$$

$$\begin{split} \frac{\mathrm{d}}{\mathrm{d}t} \int_{\Omega} \Phi(\cdot, \nabla \boldsymbol{u}_j) &= \int_{\Omega} D_{\boldsymbol{\xi}} \Phi(\cdot, \nabla \boldsymbol{u}_j) : \nabla \boldsymbol{u}_{j,t} \\ &= -\int_{\Omega} \nabla \mathrm{div} \, D_{\boldsymbol{\xi}} \Phi(\cdot, \nabla \boldsymbol{u}_j) : \left( \mathcal{P}_j \left( \mathcal{B}_j(\boldsymbol{u}_j) \nabla \mathcal{A}_j(\boldsymbol{u}_j) \right) + \mathcal{P}_j \, \boldsymbol{g} \right) \end{split}$$

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$$= -\int_{\Omega} \nabla \mathrm{div} \, D_{\boldsymbol{\xi}} \Phi(\cdot, \nabla \boldsymbol{u}_j) : (\mathcal{P}_j \left( \mathcal{B}_j(\boldsymbol{u}_j) \nabla \mathcal{A}_j(\boldsymbol{u}_j) \right) + \mathcal{P}_j \, \boldsymbol{g})$$
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$$\leq -\frac{1}{2} \int_{\Omega} \nabla \mathcal{A}_j(\boldsymbol{u}_j) : \mathcal{B}_j(\boldsymbol{u}_j) \nabla \mathcal{A}_j(\boldsymbol{u}_j) + \frac{1}{2\mu} \int_{\Omega} |\boldsymbol{g}|^2$$

$$\begin{aligned} \frac{\mathrm{d}}{\mathrm{d}t} \int_{\Omega} \Phi(\cdot, \nabla \boldsymbol{u}_{j}) &= \int_{\Omega} D_{\boldsymbol{\xi}} \Phi(\cdot, \nabla \boldsymbol{u}_{j}) : \nabla \boldsymbol{u}_{j,t} \\ &= -\int_{\Omega} \nabla \mathrm{div} \, D_{\boldsymbol{\xi}} \Phi(\cdot, \nabla \boldsymbol{u}_{j}) : (\mathcal{P}_{j} \left(\mathcal{B}_{j}(\boldsymbol{u}_{j}) \nabla \mathcal{A}_{j}(\boldsymbol{u}_{j})\right) + \mathcal{P}_{j} \, \boldsymbol{g}) \\ &= -\int_{\Omega} \nabla \mathcal{A}_{j}(\boldsymbol{u}_{j}) : \mathcal{B}_{j}(\boldsymbol{u}_{j}) \nabla \mathcal{A}_{j}(\boldsymbol{u}_{j}) + \int_{\Omega} \nabla \mathcal{A}_{j}(\boldsymbol{u}_{j}) : \boldsymbol{g} \\ &\leq -\frac{1}{2} \int_{\Omega} \nabla \mathcal{A}_{j}(\boldsymbol{u}_{j}) : \mathcal{B}_{j}(\boldsymbol{u}_{j}) \nabla \mathcal{A}_{j}(\boldsymbol{u}_{j}) + \frac{1}{2\mu} \int_{\Omega} |\boldsymbol{g}|^{2} \\ &\sup_{0 < t < T} \int_{\Omega} \Phi(\cdot, \nabla \boldsymbol{u}_{j}) + \frac{1}{2} \int_{0}^{T} \int_{\Omega} \nabla \mathcal{A}_{j}(\boldsymbol{u}_{j}) \cdot \mathcal{B}_{j}(\boldsymbol{u}_{j}) \nabla \mathcal{A}_{j}(\boldsymbol{u}_{j}) \\ &\leq 2 \int_{\Omega} \Phi(\cdot, \nabla \boldsymbol{u}_{0,j}) + \frac{1}{\mu} \int_{0}^{T} \int_{\Omega} |\boldsymbol{g}|^{2}. \end{aligned}$$

$$\begin{split} & \boldsymbol{u}_{j} - \text{uniformly bounded in } L^{\infty}(0,T,W^{1,p}(\Omega)) \\ & \mathcal{A}_{j}(\boldsymbol{u}_{j}) - \text{uniformly bounded in } L^{2}(0,T,H^{1}(\Omega)) \\ & \boldsymbol{u}_{j,t} = -\text{div} \, \mathcal{P}_{j} \left( \mathcal{B}_{j}(\boldsymbol{u}_{j}) \nabla \mathcal{A}_{j}(\boldsymbol{u}_{j}) \right) + \text{div} \, \mathcal{P}_{j} \, \boldsymbol{g} \\ & \boldsymbol{u}_{j,t} - \text{uniformly bounded in } L^{2}(0,T,H^{-1}(\Omega)) \\ & \implies \boldsymbol{u}_{j} \rightarrow \boldsymbol{u} \text{ in } C([0,T],L^{q}(\Omega)), \quad q < p^{*} \end{split}$$

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Mazur's lemma, integration by parts

$$\implies \lim_{j \to \infty} \int_0^T \int_{\Omega} (D\Phi(\cdot, \nabla \boldsymbol{u}_j) - D\Phi(\cdot, \nabla \boldsymbol{u})) \cdot (\nabla \boldsymbol{u}_j - \nabla \boldsymbol{u}) = 0$$

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$$\implies D_{\xi} \Phi(\cdot, \nabla u_j) \to D_{\xi} \Phi(\cdot, \nabla u) \text{ in } L^s(0, T, L^{r'}(\Omega)), \quad r' < p'$$

$$\int_{0}^{T} \int_{\Omega} (\mathcal{A}_{j}(\boldsymbol{u}_{j}) - \mathcal{A}(\boldsymbol{u}))^{2}$$
  
=  $-\int_{0}^{T} \int_{\Omega} (\nabla \mathcal{A}_{j}(\boldsymbol{u}_{j}) - \nabla \mathcal{A}(\boldsymbol{u})) \cdot (\mathcal{P}_{j} D_{\boldsymbol{\xi}} \Phi(\cdot, \nabla \boldsymbol{u}_{j}) - \mathcal{P}_{\nabla} D_{\boldsymbol{\xi}} \Phi(\cdot, \nabla \boldsymbol{u}))$ 

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$$\mathcal{P}_{j}D_{\boldsymbol{\xi}}\Phi(\cdot,\nabla\boldsymbol{u}_{j}) - \mathcal{P}_{\nabla}D_{\boldsymbol{\xi}}\Phi(\cdot,\nabla\boldsymbol{u})$$

$$= (\mathcal{P}_{j}D_{\boldsymbol{\xi}}\Phi(\cdot,\nabla\boldsymbol{u}_{j}) - \mathcal{P}_{j}D_{\boldsymbol{\xi}}\Phi(\cdot,\nabla\boldsymbol{u}))$$

$$+ (\mathcal{P}_{j}D_{\boldsymbol{\xi}}\Phi(\cdot,\nabla\boldsymbol{u}) - \mathcal{P}_{\nabla}D_{\boldsymbol{\xi}}\Phi(\cdot,\nabla\boldsymbol{u}))$$

$$=: \mathcal{P}_{j}M_{j} + N_{j}.$$

 $N_j \rightarrow 0$  in  $L^2(0, T, L^2(\Omega))$ 

$$M_j = D_{\boldsymbol{\xi}} \Phi(\cdot, \nabla \boldsymbol{u}_j) - D_{\boldsymbol{\xi}} \Phi(\cdot, \nabla \boldsymbol{u})$$

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$$\|\mathcal{P}_{j}M_{j}(t,\cdot)\|_{L^{2}(\Omega)} \leq \|\mathcal{P}_{j}M_{j}(t,\cdot)\|^{\vartheta}_{\dot{H}^{2}(\Omega)}\|\mathcal{P}_{j}M_{j}(t,\cdot)\|^{1-\vartheta}_{\dot{H}^{-\sigma}(\Omega)}$$

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 $\mathcal{P}_j D_{\boldsymbol{\xi}} \Phi(\cdot, \nabla \boldsymbol{u}_j) \to \mathcal{P}_{\nabla} D_{\boldsymbol{\xi}} \Phi(\cdot, \nabla \boldsymbol{u}) \text{ in } L^2(\Omega_T)$ 

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### $\implies \mathcal{A}_j(\boldsymbol{u}_j) \to \mathcal{A}(\boldsymbol{u}) \text{ in } L^2(\Omega_T)$

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 $\mathcal{P}_{j}D_{\boldsymbol{\xi}}\Phi(\cdot,\nabla\boldsymbol{u}_{j}) \to \mathcal{P}_{\nabla}D_{\boldsymbol{\xi}}\Phi(\cdot,\nabla\boldsymbol{u}) \text{ in } L^{2}(\Omega_{T})$   $\implies \mathcal{A}_{j}(\boldsymbol{u}_{j}) \to \mathcal{A}(\boldsymbol{u}) \text{ in } L^{2}(\Omega_{T})$   $\implies \mathcal{B}_{j}(\boldsymbol{u}_{j}) \to \mathcal{B}(\boldsymbol{u}) \text{ in } L^{2}(\Omega_{T})$   $\implies \mathcal{B}_{j}(\boldsymbol{u}_{j})\nabla\mathcal{A}_{i}(\boldsymbol{u}_{j}) \to \mathcal{B}(\boldsymbol{u})\nabla\mathcal{A}(\boldsymbol{u}) \text{ in } L^{1}(\Omega_{T})$ 

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$$\implies \mathcal{B}_{j}(\boldsymbol{u}_{j})\nabla\mathcal{A}_{j}(\boldsymbol{u}_{j}) \to \mathcal{B}(\boldsymbol{u})\nabla\mathcal{A}(\boldsymbol{u}) \text{ in } L^{1}(\Omega_{T})$$

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#### Scope

Generalizations:

unbounded  $\mathbb{B}$ 

 $|\mathbb{B}(t, x, \boldsymbol{w}, \boldsymbol{\xi}, \boldsymbol{z})| \le c_2 \left( f_2(t, x) + |\boldsymbol{w}|^{q_0} + |\boldsymbol{\xi}|^{q_1} + |\boldsymbol{z}|^{q_2} 
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boundary conditions; we need a mild regularity assumption on Ω
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## Summary

We obtained global-in-time existence of weak solutions to

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## Thank you for your attention!